



Introduction to deep learning

Andreas Damianou

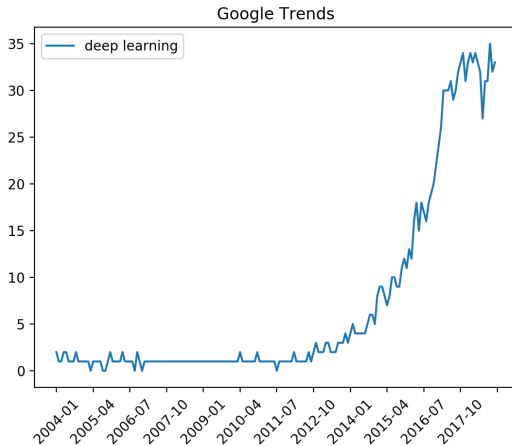
Amazon, Cambridge, UK

Royal Statistical Society, London

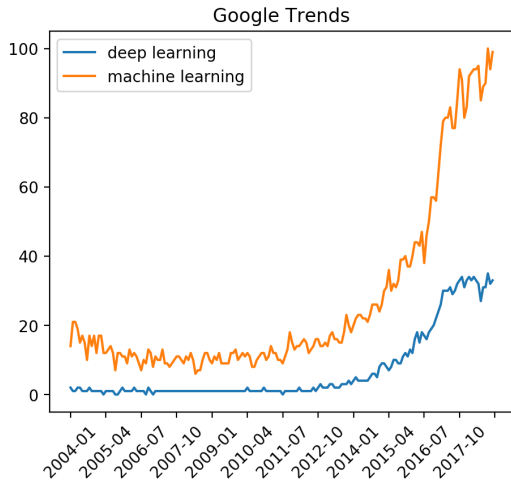
13 Dec. 2018

http://adamian.github.io/talks/Damianou_DL_tutorial_18.ipynb

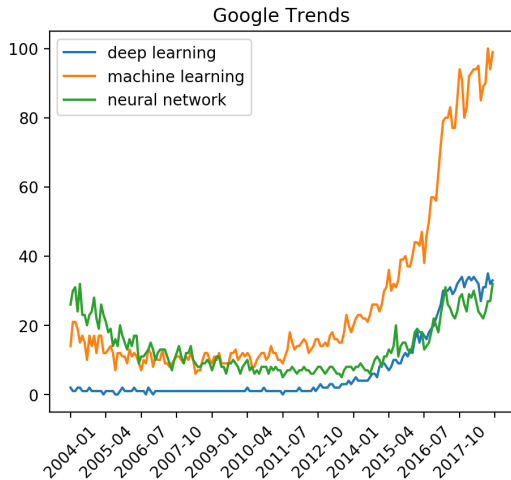
Starting with a cliché...



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Starting with a cliché...



Deep neural networks: hierarchical function definitions

A neural network is a composition of functions (layers), each parameterized with a *weight vector* \mathbf{w}_l . E.g. for 2 layers:

$$f_{\text{net}} = h_2(h_1(\mathbf{x}; \mathbf{w}_1); \mathbf{w}_2).$$

Generally $f_{\text{net}} : \mathbf{x} \mapsto \mathbf{y}$ with:

$$\mathbf{h}_1 = \varphi(\mathbf{x}\mathbf{w}_1 + b_1)$$

$$\mathbf{h}_2 = \varphi(\mathbf{h}_1\mathbf{w}_2 + b_2)$$

...

$$\hat{\mathbf{y}} = \varphi(\mathbf{h}_{L-1}\mathbf{w}_L + b_L)$$

ϕ is the (non-linear) activation function.

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Defining the loss

- ▶ We have our function approximator $f_{\text{net}}(x) = \hat{y}$
- ▶ We have to define our loss (objective function) to relate this function outputs to the observed data.
- ▶ E.g. squared difference $\sum_n (y_n - \hat{y}_n)^2$ or cross-entropy

Probabilistic re-formulation

- ▶ Training minimizing loss:

$$\arg \min_{\mathbf{w}} \underbrace{\frac{1}{2} \sum_{i=1}^N (f_{\text{net}}(\mathbf{w}, x_i) - y_i)^2}_{\text{fit}} + \lambda \underbrace{\sum_i \|\mathbf{w}_i\|}_{\text{regularizer}}$$

- ▶ Equivalent probabilistic view for regression, maximizing posterior probability:

$$\arg \max_{\mathbf{w}} \underbrace{\log p(\mathbf{y}|\mathbf{x}, \mathbf{w})}_{\text{fit}} + \underbrace{\log p(\mathbf{w})}_{\text{regularizer}}$$

where $p(\mathbf{y}|\mathbf{x}, \mathbf{w}) \sim \mathcal{N}$ and $p(\mathbf{w}) \sim \text{Laplace}$

- ▶ Optimization still done with back-prop (i.e. gradient descent).

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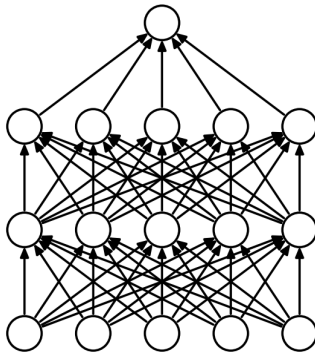
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Graphical depiction



Optimization

One layer:

$$\begin{aligned} Loss &= \frac{1}{2}(\mathbf{h} - \mathbf{y})^2 \\ \mathbf{h} &= \phi(\mathbf{x}\mathbf{w}) \\ \frac{\vartheta Loss}{\vartheta \mathbf{w}} &= \underbrace{(\mathbf{y} - \mathbf{h})}_{\epsilon} \frac{\vartheta \phi(\mathbf{x}\mathbf{w})}{\vartheta \mathbf{w}} \end{aligned}$$

Two layers:

$$\begin{aligned} Loss &= \frac{1}{2}(\mathbf{h}_2 - \mathbf{y})^2 \\ \mathbf{h}_2 &= \phi \left[\underbrace{\phi(\mathbf{x}\mathbf{w}_0)}_{\mathbf{h}_1} \mathbf{w}_1 \right] \\ \frac{\vartheta Loss}{\vartheta \mathbf{w}_0} &= \dots \\ \frac{\vartheta Loss}{\vartheta \mathbf{w}_1} &= \dots \end{aligned}$$

Derivative w.r.t \mathbf{w}_1

$$\begin{aligned}\frac{\vartheta(\mathbf{h}_2 - \mathbf{y})^2}{\vartheta \mathbf{w}_1} &= -2 \frac{1}{2} (\mathbf{h}_2 - \mathbf{y}) \frac{\vartheta \mathbf{h}_2}{\vartheta \mathbf{w}_1} = \\ &= (\mathbf{y} - \mathbf{h}_2) \frac{\vartheta \phi(\mathbf{h}_1 \mathbf{w}_1)}{\vartheta \mathbf{w}_1} = \\ &= (\mathbf{y} - \mathbf{h}_2) \frac{\vartheta \phi(\mathbf{h}_1 \mathbf{w}_1)}{\vartheta \mathbf{h}_1 \mathbf{w}_1} \frac{\vartheta \mathbf{h}_1 \mathbf{w}_1}{\vartheta \mathbf{w}_1} = \\ &= \underbrace{(\mathbf{y} - \mathbf{h}_2)}_{\epsilon_2} \underbrace{\frac{\vartheta \phi(\mathbf{h}_1 \mathbf{w}_1)}{\vartheta \mathbf{h}_1 \mathbf{w}_1}}_{g_1} \mathbf{h}_1^T\end{aligned}$$

\mathbf{h}_1 is computed during the *forward pass*.

Derivative w.r.t \mathbf{w}_0

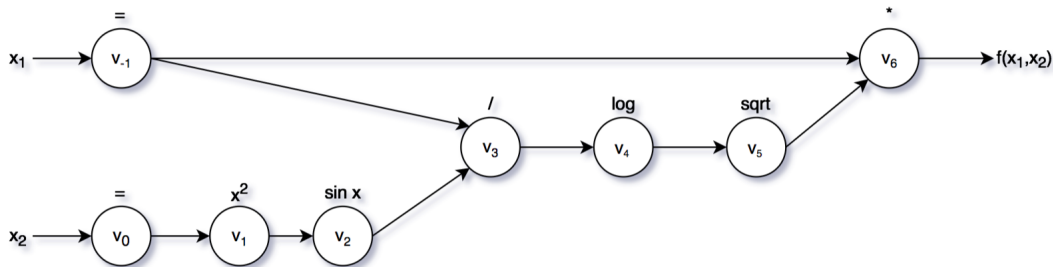
$$\begin{aligned}\frac{\partial (\mathbf{h}_2 - \mathbf{y})^2}{\partial \mathbf{w}_0} &= -2 \frac{1}{2} (\mathbf{h}_2 - \mathbf{y}) \frac{\partial \mathbf{h}_2}{\partial \mathbf{w}_0} = \\ &= (\mathbf{y} - \mathbf{h}_2) \frac{\partial \phi(\mathbf{h}_1 \mathbf{w}_1)}{\partial \mathbf{h}_1 \mathbf{w}_1} \frac{\partial \mathbf{h}_1 \mathbf{w}_1}{\partial \mathbf{h}_1} \frac{\partial \mathbf{h}_1}{\partial \mathbf{w}_0} = \\ &= \epsilon_2 g_1 \mathbf{w}_1^T \frac{\partial \phi(\mathbf{x} \mathbf{w}_0)}{\partial \mathbf{x} \mathbf{w}_0} \frac{\partial \mathbf{x} \mathbf{w}_0}{\partial \mathbf{w}_0} = \\ &= \epsilon_2 g_1 \mathbf{w}_1^T \underbrace{\frac{\partial \phi(\mathbf{x} \mathbf{w}_0)}{\partial \mathbf{x} \mathbf{w}_0}}_{g_0} \mathbf{x}^T\end{aligned}$$

Propagation of error is just the chain rule.

Go to notebook!

Automatic differentiation

Example: $f(x_1, x_2) = x_1 \sqrt{\log \frac{x_1}{\sin(x_2^2)}}$ has symbolic graph:



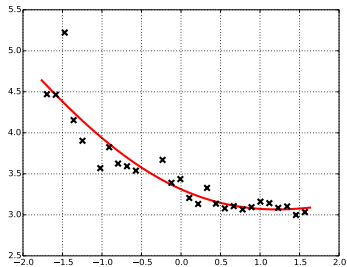
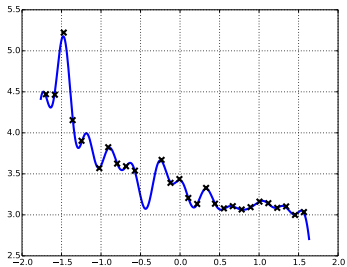
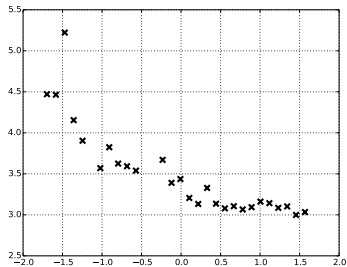
(image: sanyamkapoor.com)

Back to notebook!

We're far from done...

- ▶ How to initialize the (so many) parameters?
- ▶ How to pick the right architecture?
- ▶ Layers and parameters co-adapt.
- ▶ Multiple local optima in optimization surface.
- ▶ Numerical problems.
- ▶ Bad behaviour of composite function (e.g. problematic gradient distribution).
- ▶ *OVERFITTING*

Curve fitting [skip]



Taming the dragon



Lottery ticket hypothesis

Might provide intuition for many of the tricks used.

- ▶ Optimization landscape: multiple optima and difficult to navigate
- ▶ Over-parameterized networks contain multiple sub-networks (“lottery tickets”)
- ▶ “Winning ticket”: a lucky sub-network found a good solution
- ▶ Over-parameterization: more tickets, higher winning probability
- ▶ Of course this means we have to prune or at least regularize.

(Frankle and Carbin (2018))

“Tricks”

- ▶ Smart initializations
- ▶ ReLU: better behaviour of gradients
- ▶ Early stopping: prevent overfitting
- ▶ Dropout
- ▶ Batch-normalization
- ▶ Transfer/meta-learning/BO: guide the training with another model
- ▶ many other “tricks”

Vanishing and exploding gradients

$$\begin{aligned}\frac{\partial (\mathbf{h}_2 - \mathbf{y})^2}{\partial \mathbf{w}_0} &= -2 \frac{1}{2} (\mathbf{h}_2 - \mathbf{y}) \frac{\partial \mathbf{h}_2}{\partial \mathbf{w}_0} = \\ &= (\mathbf{y} - \mathbf{h}_2) \frac{\frac{\partial \phi(\mathbf{h}_1 \mathbf{w}_1)}{\partial \mathbf{h}_1 \mathbf{w}_1} \frac{\partial \mathbf{h}_1 \mathbf{w}_1}{\partial \mathbf{h}_1} \frac{\partial \mathbf{h}_1}{\partial \mathbf{w}_0}}{\frac{\partial \mathbf{h}_1 \mathbf{w}_1}{\partial \mathbf{h}_1 \mathbf{w}_1}} = \\ &= \epsilon_2 g_1 \mathbf{w}_1^T \frac{\frac{\partial \phi(\mathbf{x} \mathbf{w}_0)}{\partial \mathbf{x} \mathbf{w}_0} \frac{\partial \mathbf{x} \mathbf{w}_0}{\partial \mathbf{w}_0}}{\mathbf{x} \mathbf{w}_0} = \\ &= \epsilon_2 g_1 \mathbf{w}_1^T \underbrace{\frac{\partial \phi(\mathbf{x} \mathbf{w}_0)}{\partial \mathbf{x} \mathbf{w}_0}}_{g_0} \mathbf{x}^T\end{aligned}$$

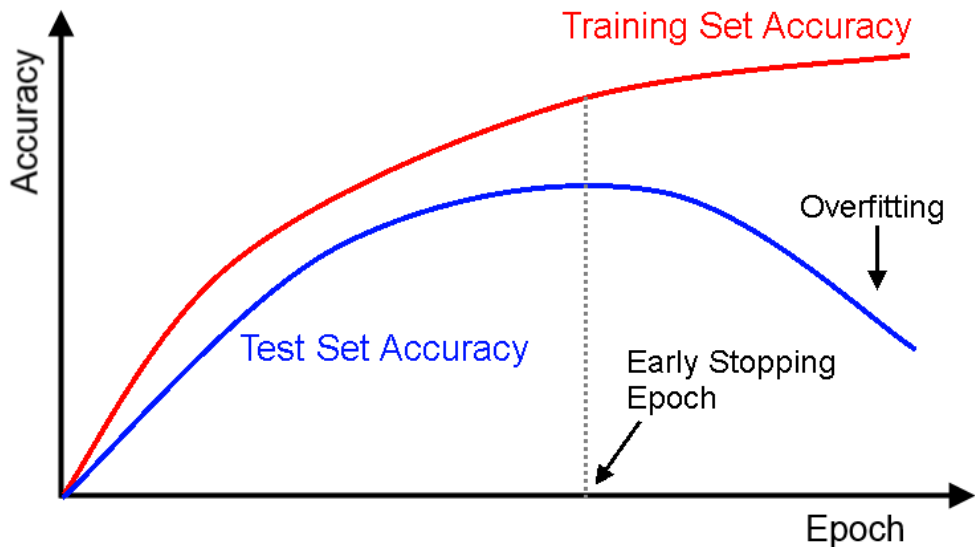
- ReLU: an activation function leading to well-behaved gradients.

Vanishing and exploding gradients

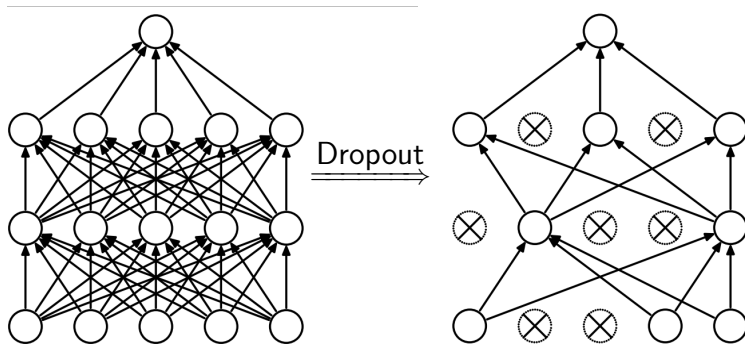
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Early stopping



Dropout



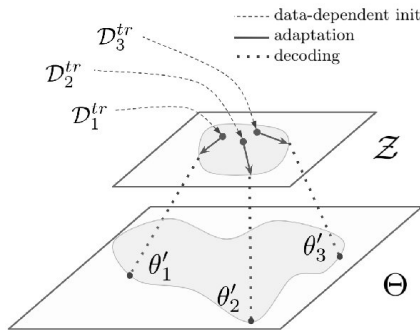
- ▶ Randomly drop units during training.
- ▶ Prevents units from co-adapting too much and prevents overfitting.

Batch-normalization

- ▶ Normalize each layer's output so e.g. $\mu = 0, \sigma = 1$
- ▶ Reduces covariate shift (data distribution changes)
- ▶ Less co-adaptation of layers
- ▶ Overall: faster convergence

Meta-learning

- ▶ Optimize the neural network model with the help of another model.
- ▶ The helper model might be allowed to learn from multiple datasets.

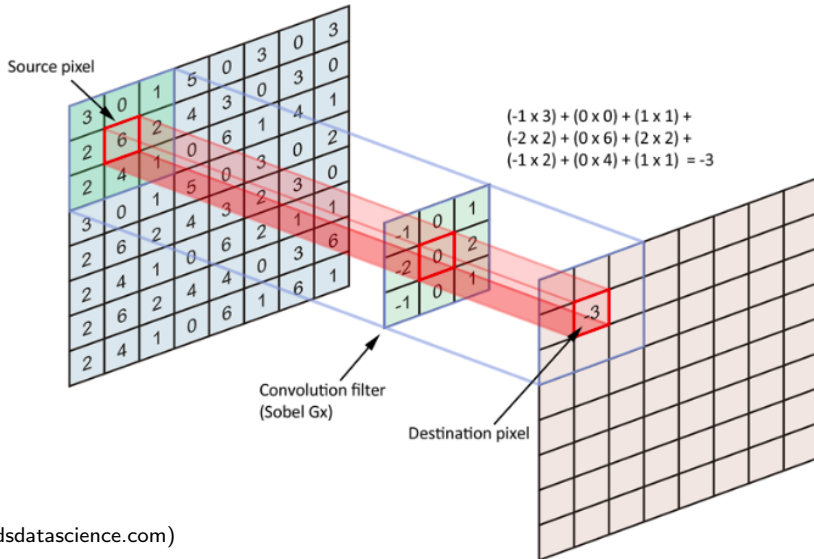


(image: Rusu et al. 2018 - LEO)

Bayesian HPO

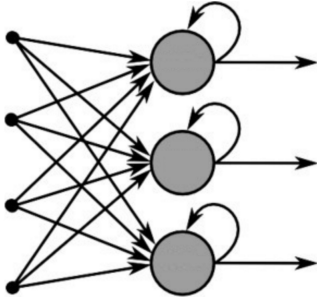
- ▶ Hyperparameters: learning rate, weight decay, architectures, learning protocols
- ▶ Optimize them using Bayesian optimization
- ▶ Prediction of learning curves. Can speed up HPO in a bandit setting
- ▶ Example: <https://xfer.readthedocs.io/en/master/demos/xfer-hpo.html>

Convolutional NN

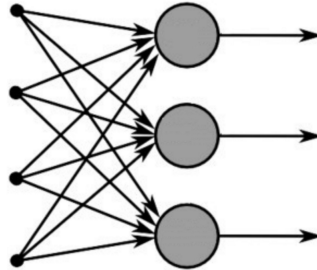


(image: towardsdatascience.com)

Recurrent NN



Recurrent Neural Network



Feed-Forward Neural Network

image: towardsdatascience.com

Deployment: Transfer learning

Training neural networks from scratch is not practical as this requires:

- ▶ a lot of data
- ▶ expertise
- ▶ compute (e.g. GPU machines)

Solution:

- ▶ Transfer learning. Repurposing pre-trained neural networks to solve new tasks.
- ▶ A library for transfer learning: <https://github.com/amzn/xfer>

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Bayesian deep learning

*We saw that optimizing the parameters is a challenge.
Why not marginalize them out completely?*

Probabilistic re-formulation

- ▶ Training minimizing loss:

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- ▶ Optimization still done with back-prop (i.e. gradient descent).

Integrating out weights

$$D := (\mathbf{x}, \mathbf{y})$$

$$p(w|D) = \frac{p(D|w)p(w)}{p(D) = \int p(D|w)p(w)\mathrm{d}w}$$

Inference

- ▶ $p(D)$ (and hence $p(w|D)$) is difficult to compute because of the nonlinear way in which w appears through g .
- ▶ Attempt at *variational inference*:

$$\underbrace{\text{KL}(q(w; \theta) \parallel p(w|D))}_{\text{minimize}} = \log(p(D)) - \underbrace{\mathcal{L}(\theta)}_{\text{maximize}}$$

where

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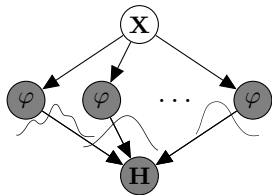
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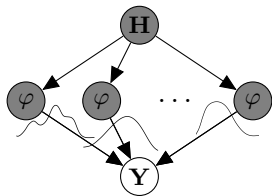
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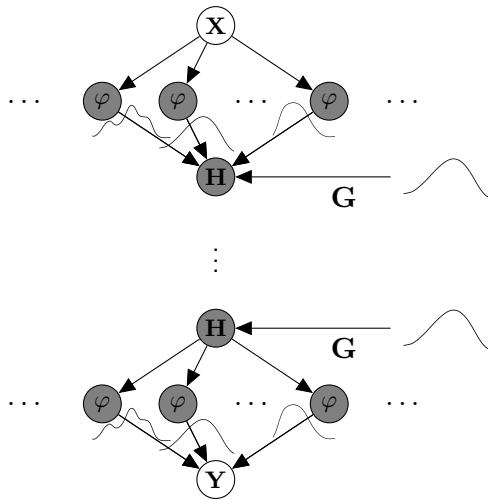
Bayesian neural network *(what we saw before)*



...



From NN to GP



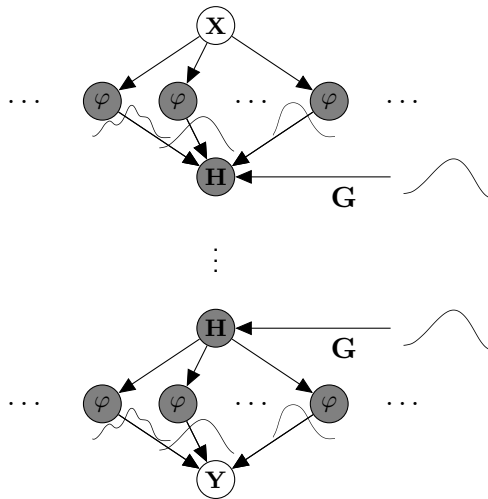
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► GP: ϕ is ∞ -dimensional so:
 $\mathbf{H}_2 = f_2(\mathbf{H}_1; \theta_2) + \epsilon$

► NN: $p(\mathbf{W})$

► GP: $p(f(\cdot))$

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- ▶ NN: $p(\mathbf{W})$
- ▶ GP: $p(f(\cdot))$

Summary

- ▶ Vanilla feedforward NN with backpropagation (chain rule)
- ▶ Automatic differentiation
- ▶ Practical issues and solutions (“tricks”)
- ▶ Understanding the challenges: optimization landscape and capacity
- ▶ ConvNets and RNNs
- ▶ Transfer Learning for practical use
- ▶ Bayesian NNs

Conclusions

- ▶ NNs are mathematically simple; challenge is in how to optimize them.
- ▶ Data efficiency? Uncertainty calibration? Interpretability? Safety? ...